

Robotic Surgical Training



A Comparative Human-centric Analysis of Virtual Reality Simulation and Physical Dry Lab Exercises

Michael Kasman¹, Ziheng Wang², Marco Martinez³, Robert Rege⁴, Herbert Zeh⁴, Daniel Scott⁴, and Ann Majewicz Fey^{2,4}

1. Department of Electrical & Computer Engineering, University of Texas at Dallas, Richardson, Texas

2. Department of Mechanical Engineering, University of Texas at Dallas, Richardson, Texas

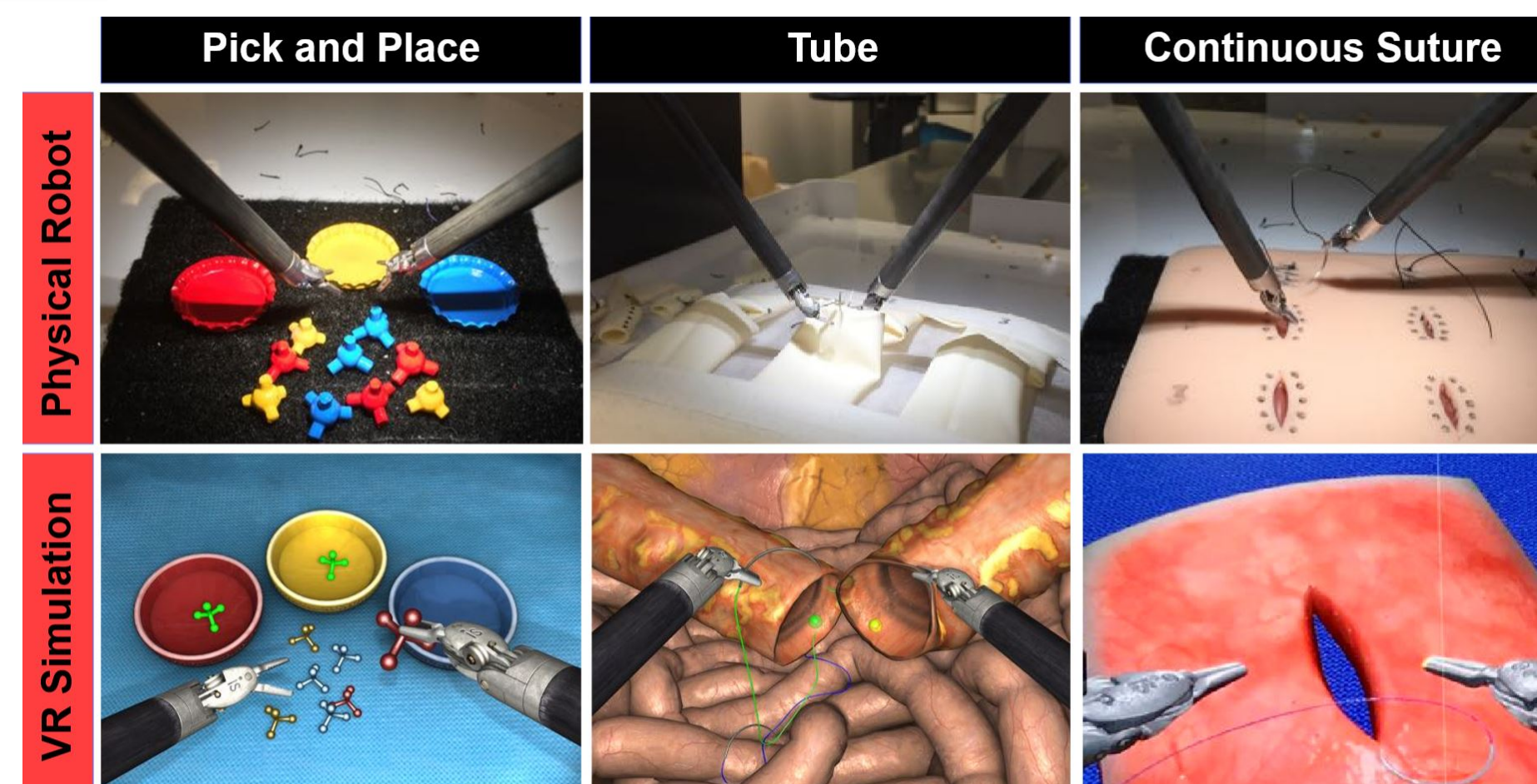
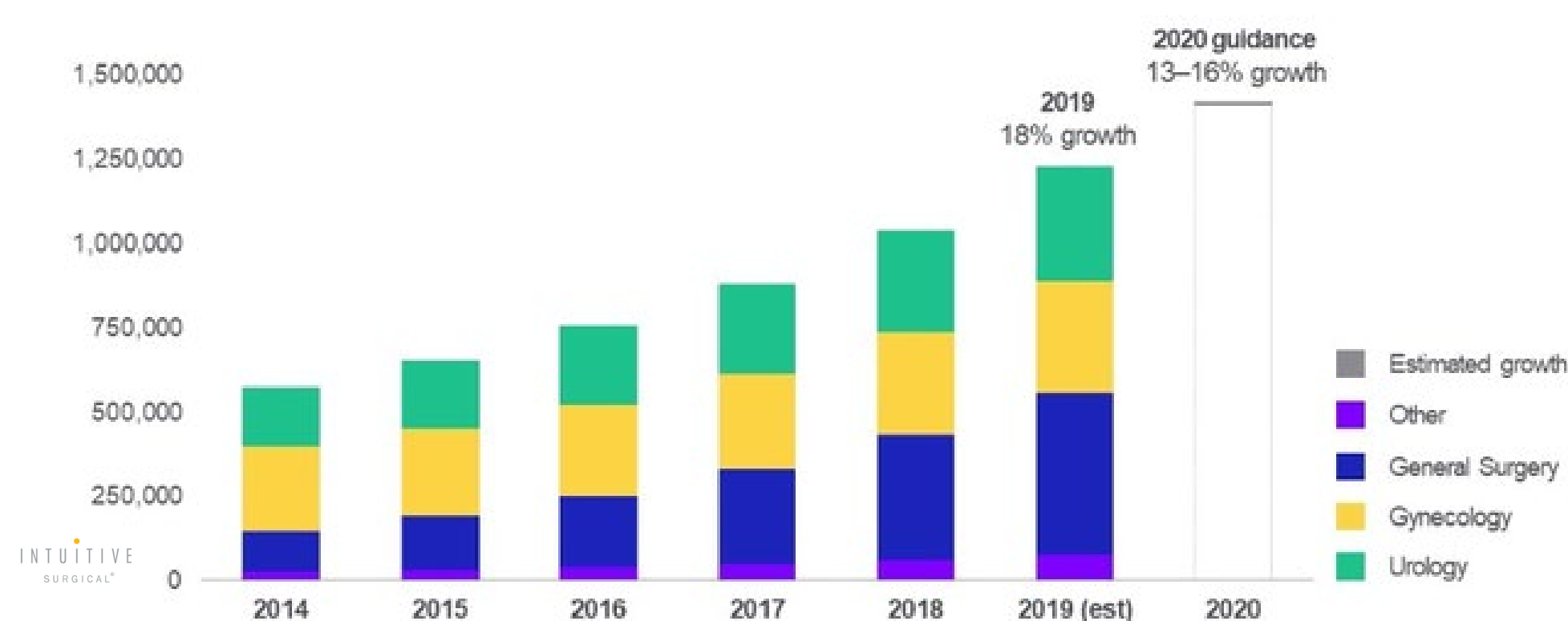
3. Department of Surgery, Naval Medical Center, San Diego, California

4. Department of Surgery, University of Texas Southwestern Medical Center, Dallas, Texas

Virtual reality and dry lab simulation to train surgical residents

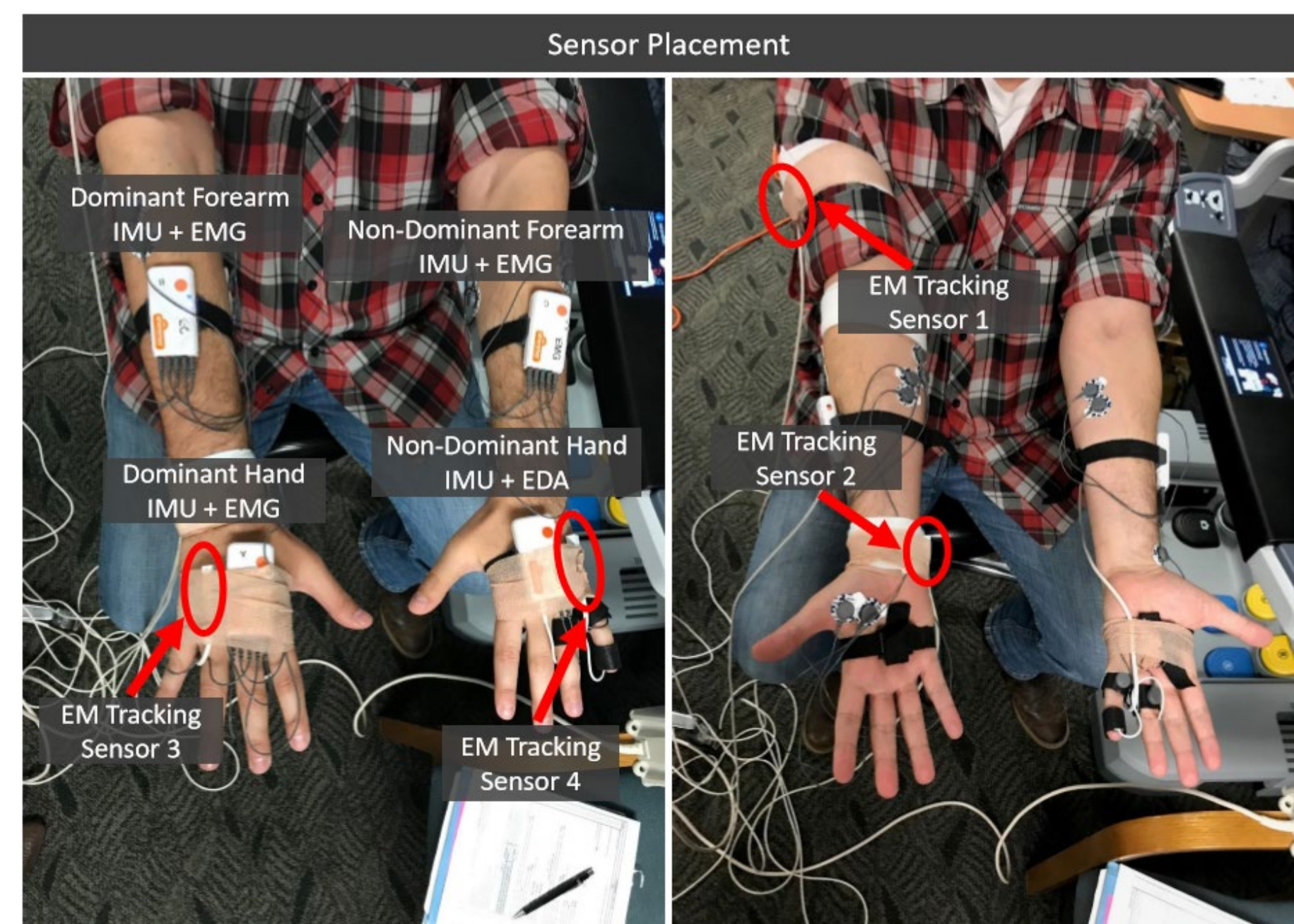
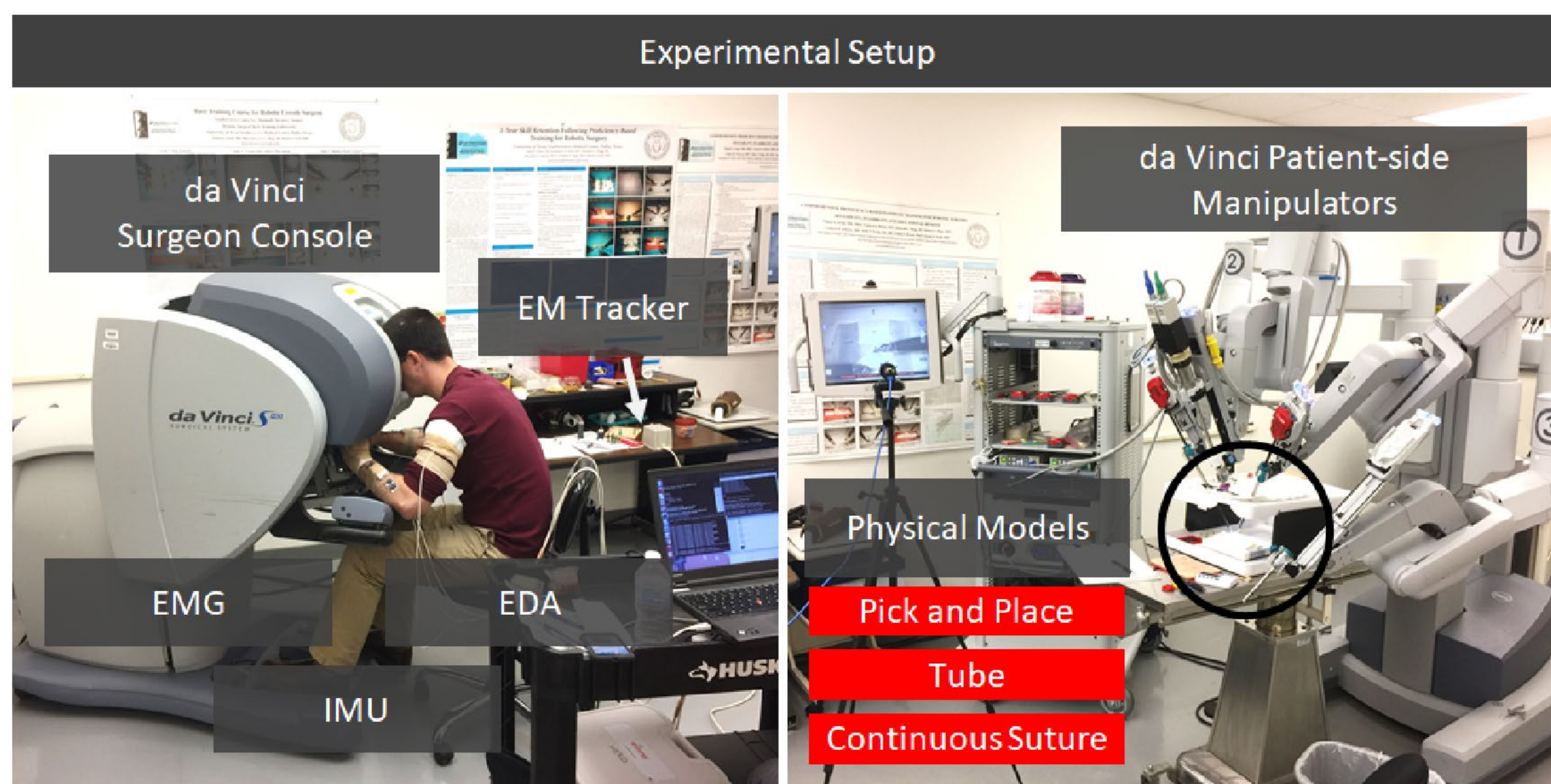
- Robotic-minimally invasive surgery (RMIS) is being adopted in an increasing range of surgical specialties

Worldwide procedure trend



- Surgical training systems developed to overcome the steep learning curve
- Are virtual reality and dry lab training skills learned interchangeable?

Measuring human operator kinematics and physiological response



Data Collection:

- Total of 72 individual experiment trials containing human physiological response signals
 - Surface muscle **electromyography (EMG)**
 - **Electrodermal response (EDA)**
 - Motion kinematic data of user dominant and non-dominant arms: **position, angular velocity, and linear acceleration** collected from **electromagnetic (EM)** and **inertial measurement unit (IMU)** sensors.

Feature analysis between physical and simulated training exercises

- Significant differences (p -value < 0.05): **muscle activation**, **path length**, and **economy of volume**

